

# **Introduction to discrete-time filters**

Ideal and elementary filters

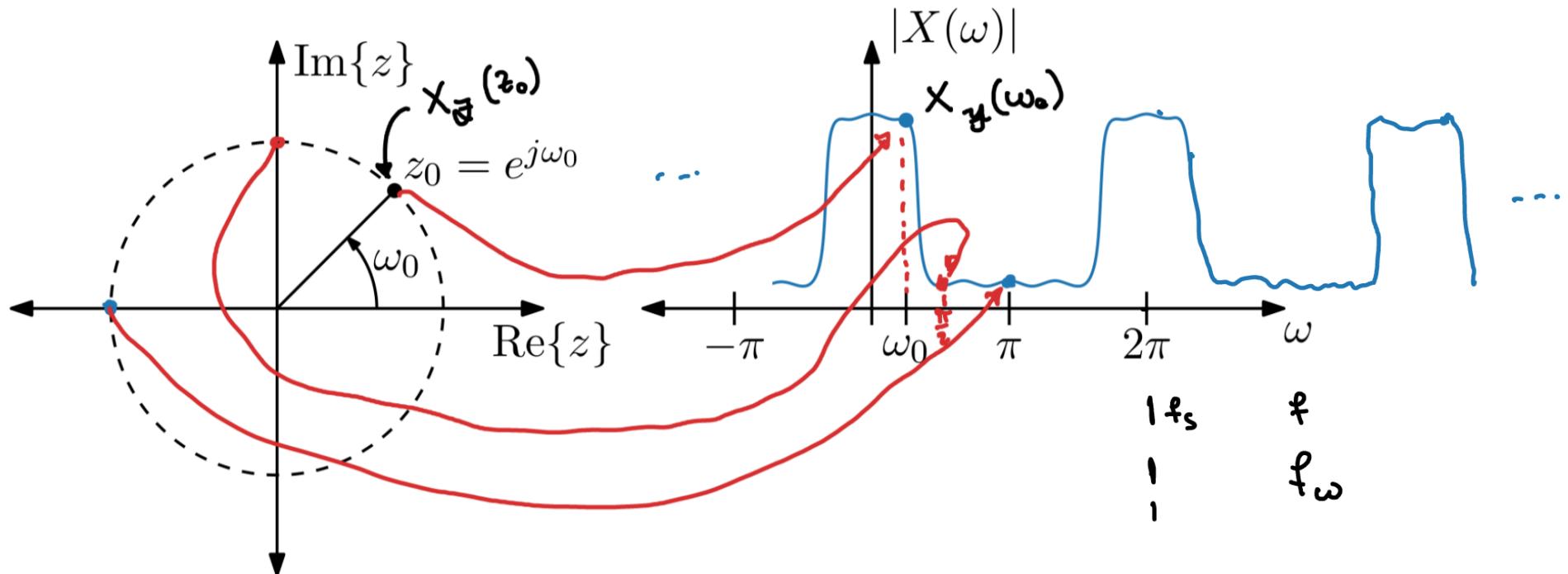
Herman Kamper

# Recap: z-transform and DTFT

$$\text{DTFT: } X(\omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$$

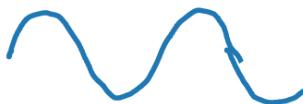
$$\text{z-transform: } X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}$$

$$X_{\frac{d}{dt}}(\omega) = X_{\frac{d}{dz}}(z) \Big|_{z=e^{j\omega}} = X_{\frac{d}{dz}}(e^{j\omega})$$



Continuous cosine:

$$x(t) = \cos(2\pi f_0 t)$$



Sample  $x(t)$  to

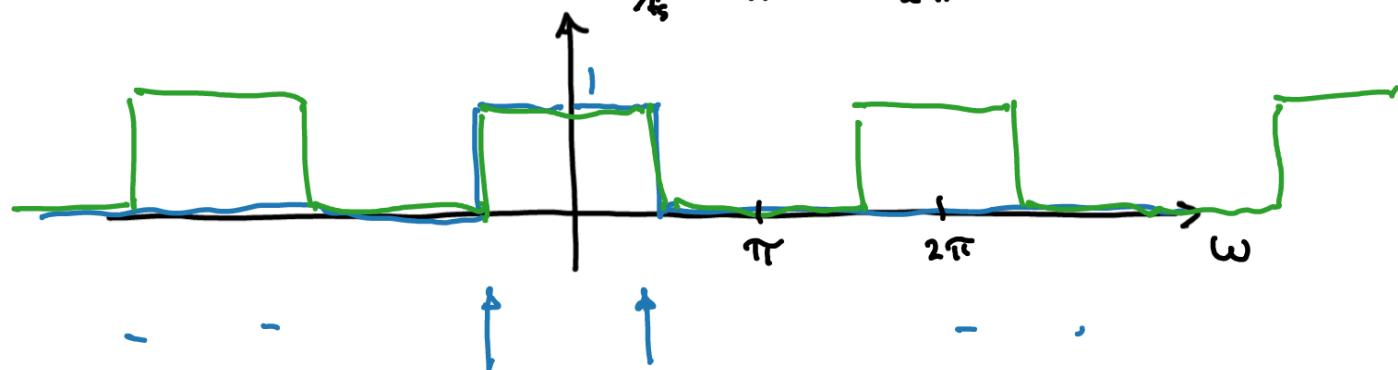
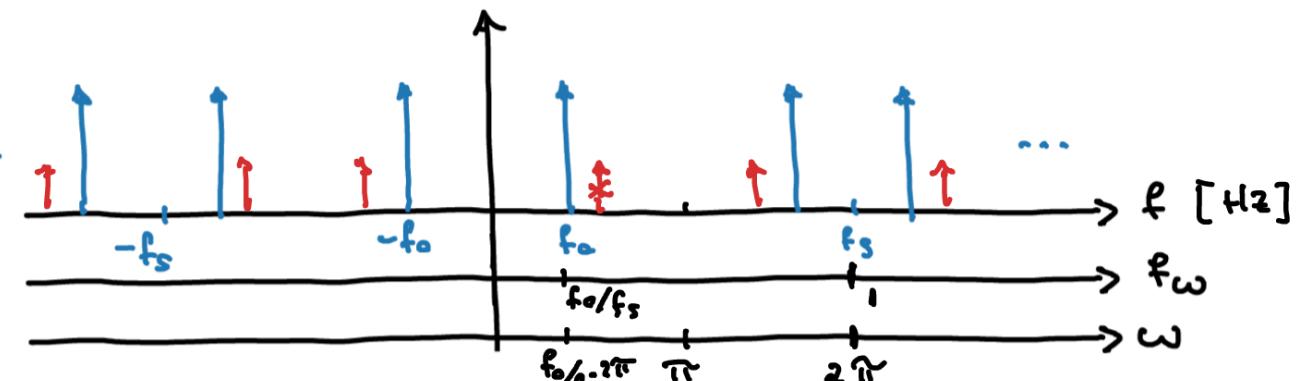
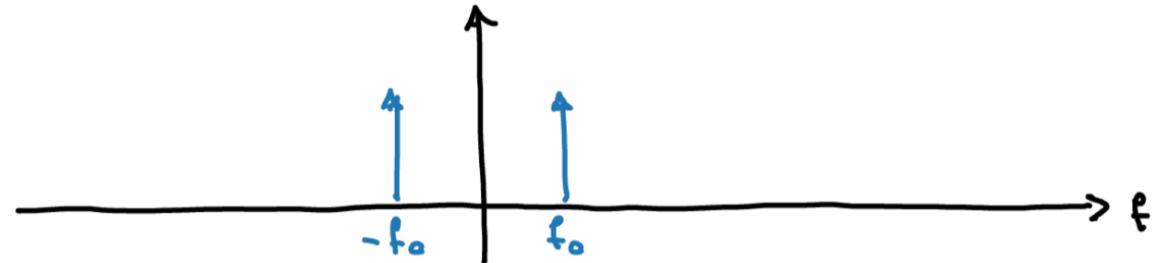
get  $x[n]$  with  $f_s$  sampling freq.

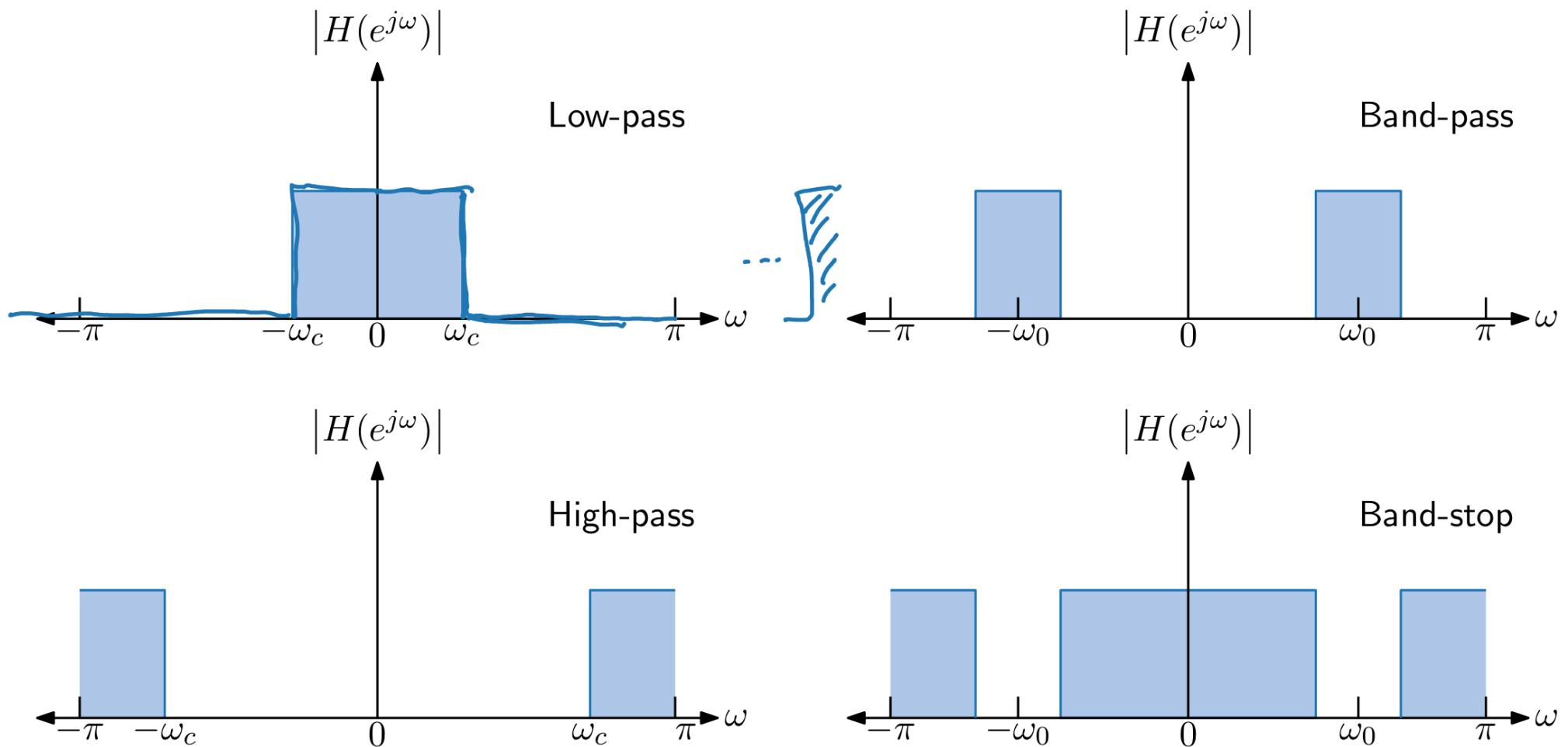


Design filter to let

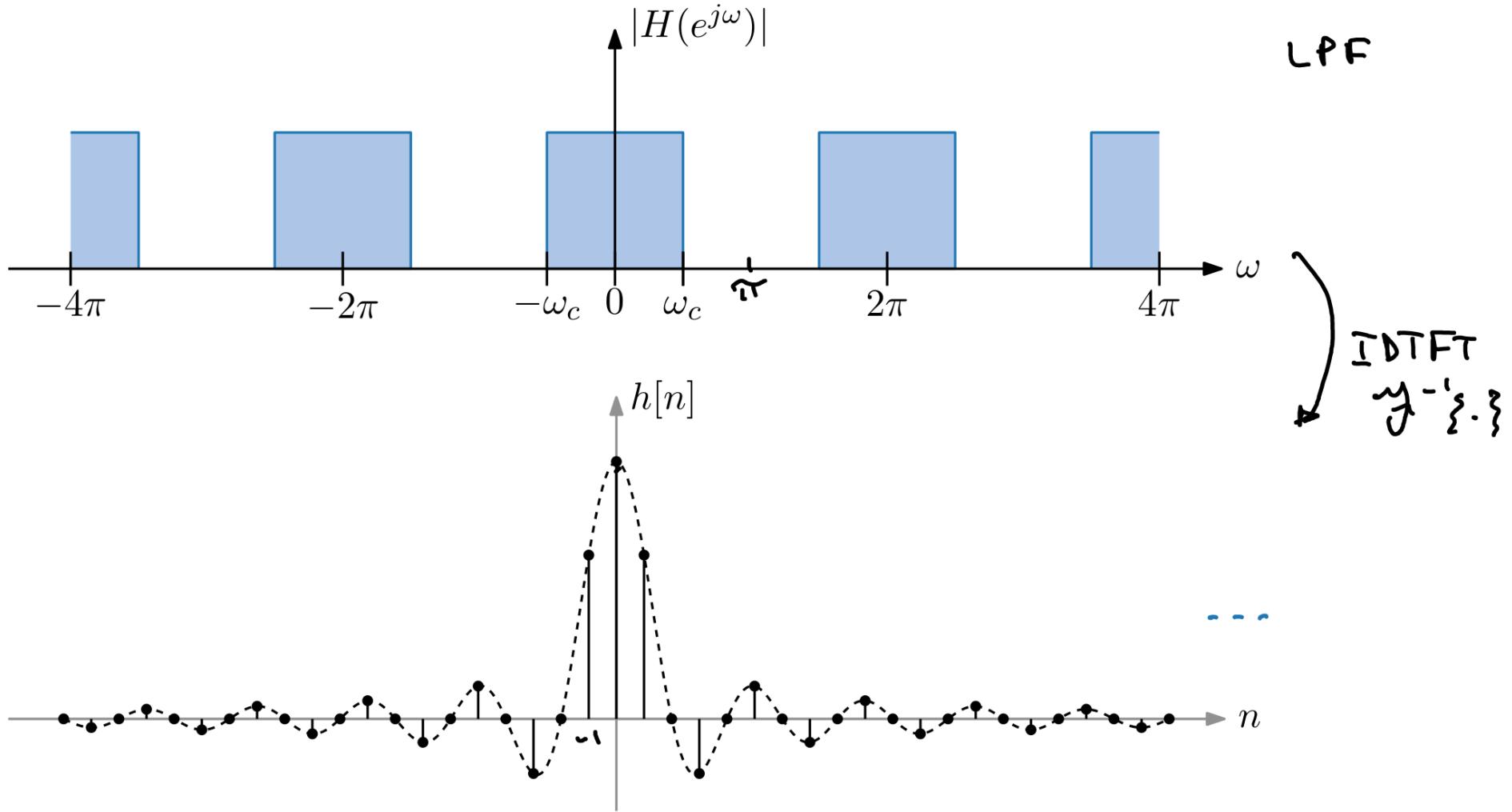
everything below

$$f_{w_0} = \frac{f_0}{f_s}$$
 in (LPF)

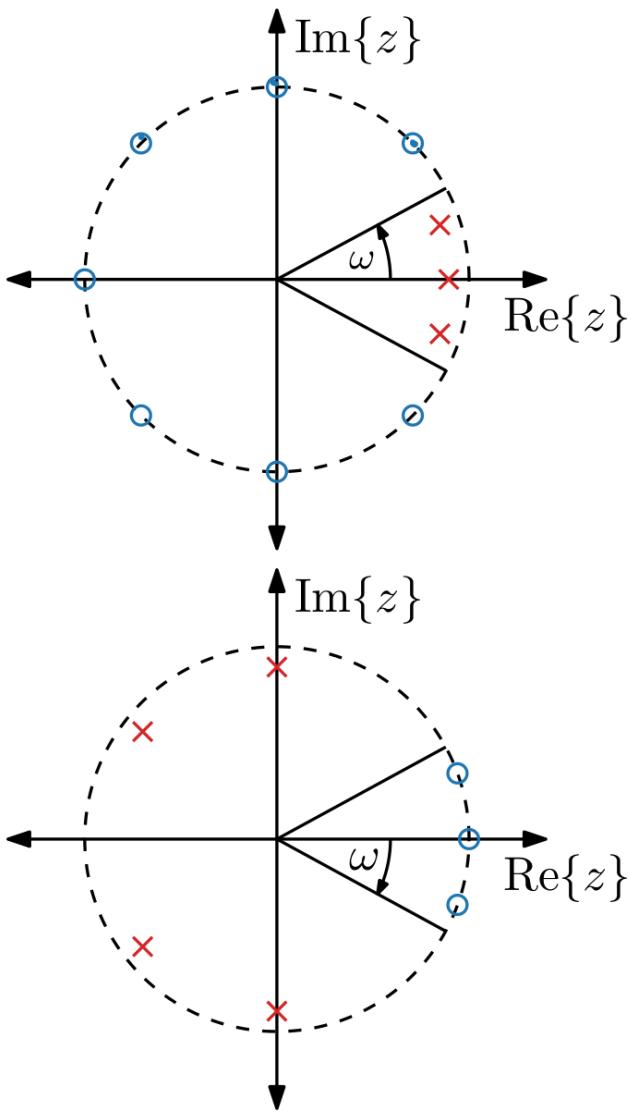




# Ideal filters are unrealisable



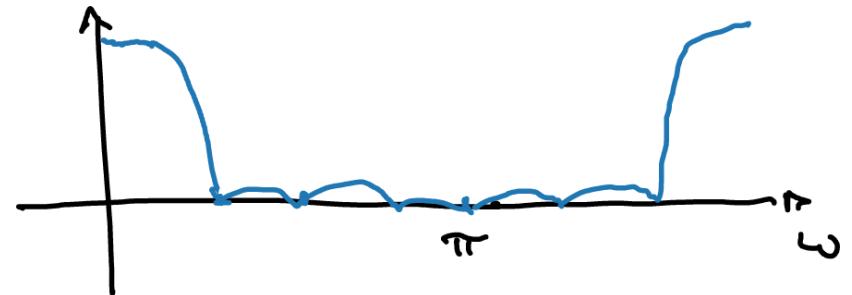
# Elementary filters



LPF

HIF

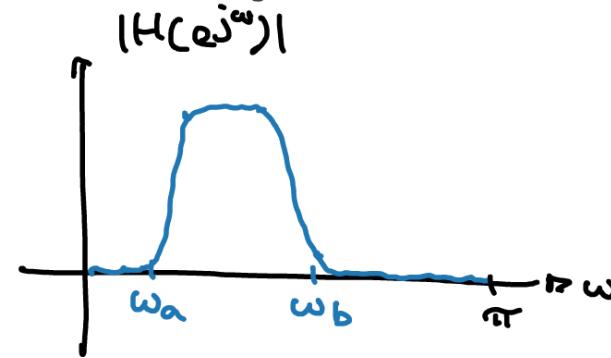
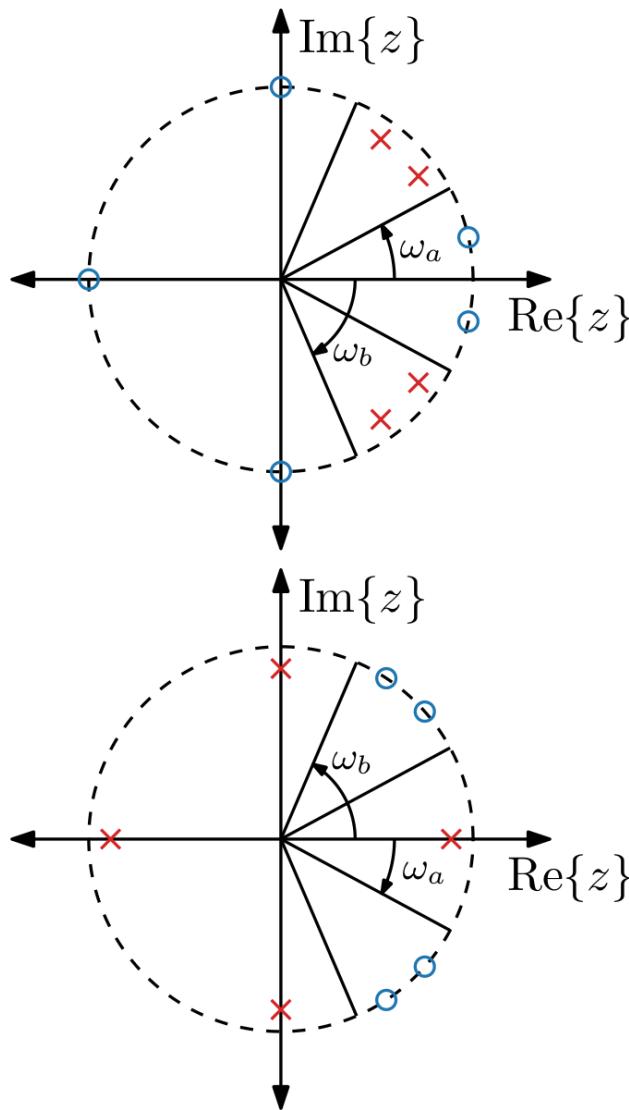
$$|H(e^{j\omega})|$$



LPF, BSF, HIF, BPF  
(1) (2) (3) (4)

# Elementary filters

LPF, BSF, HIF, BPF  
(1) (2) (3) (4)

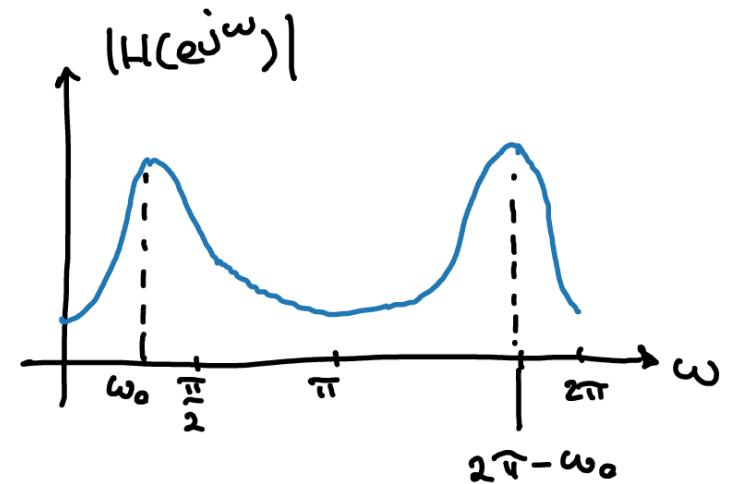
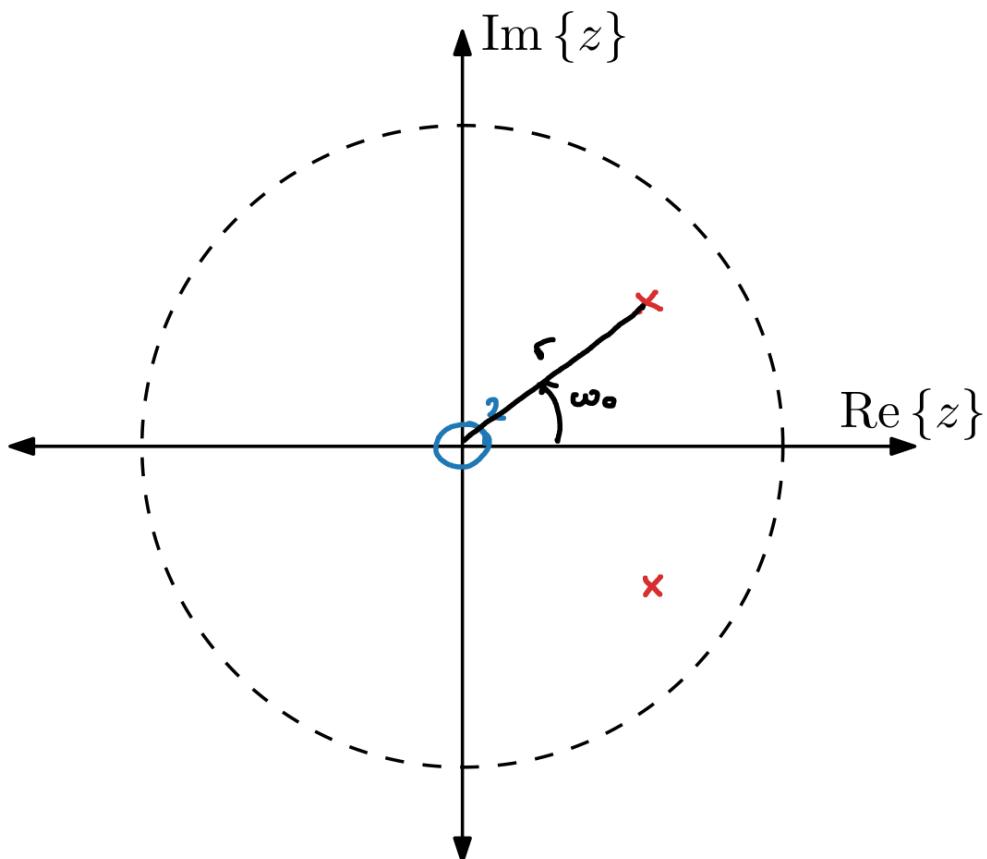


BPF

BSF

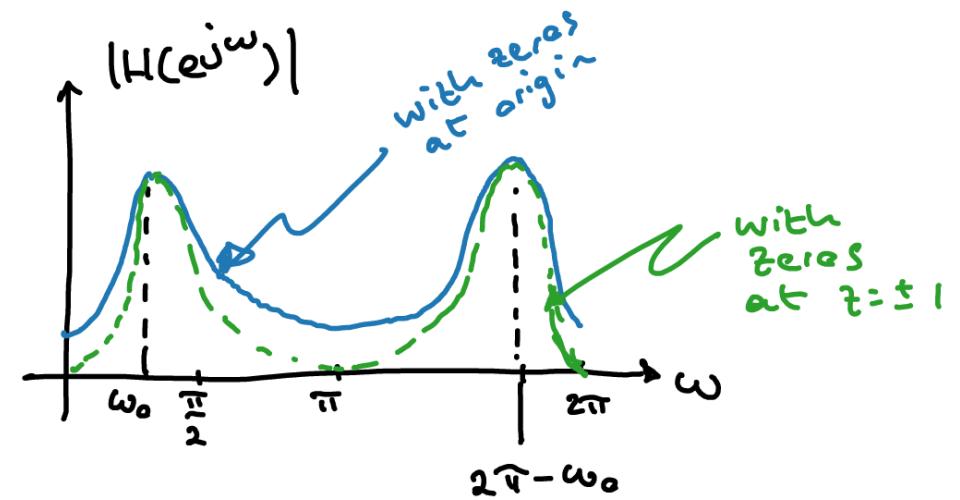
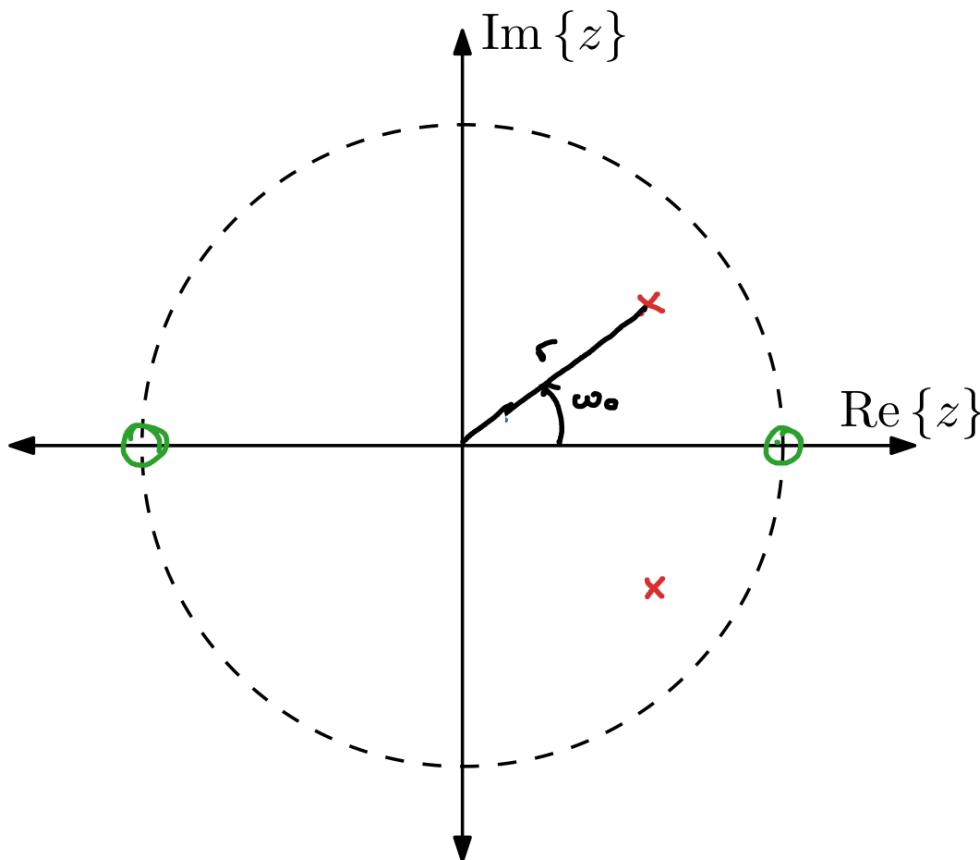
# Digital resonator: An elementary BPF

$$H(z) = \frac{b_0}{1 - (2r \cos \omega_0)z^{-1} + r^2 z^{-2}} = \frac{b_0}{(1 - re^{j\omega_0}z^{-1})(1 - re^{-j\omega_0}z^{-1})}$$
$$\frac{re^{j\omega_0}}{z}$$
$$p_{1,z} = r e^{\pm j\omega_0}$$

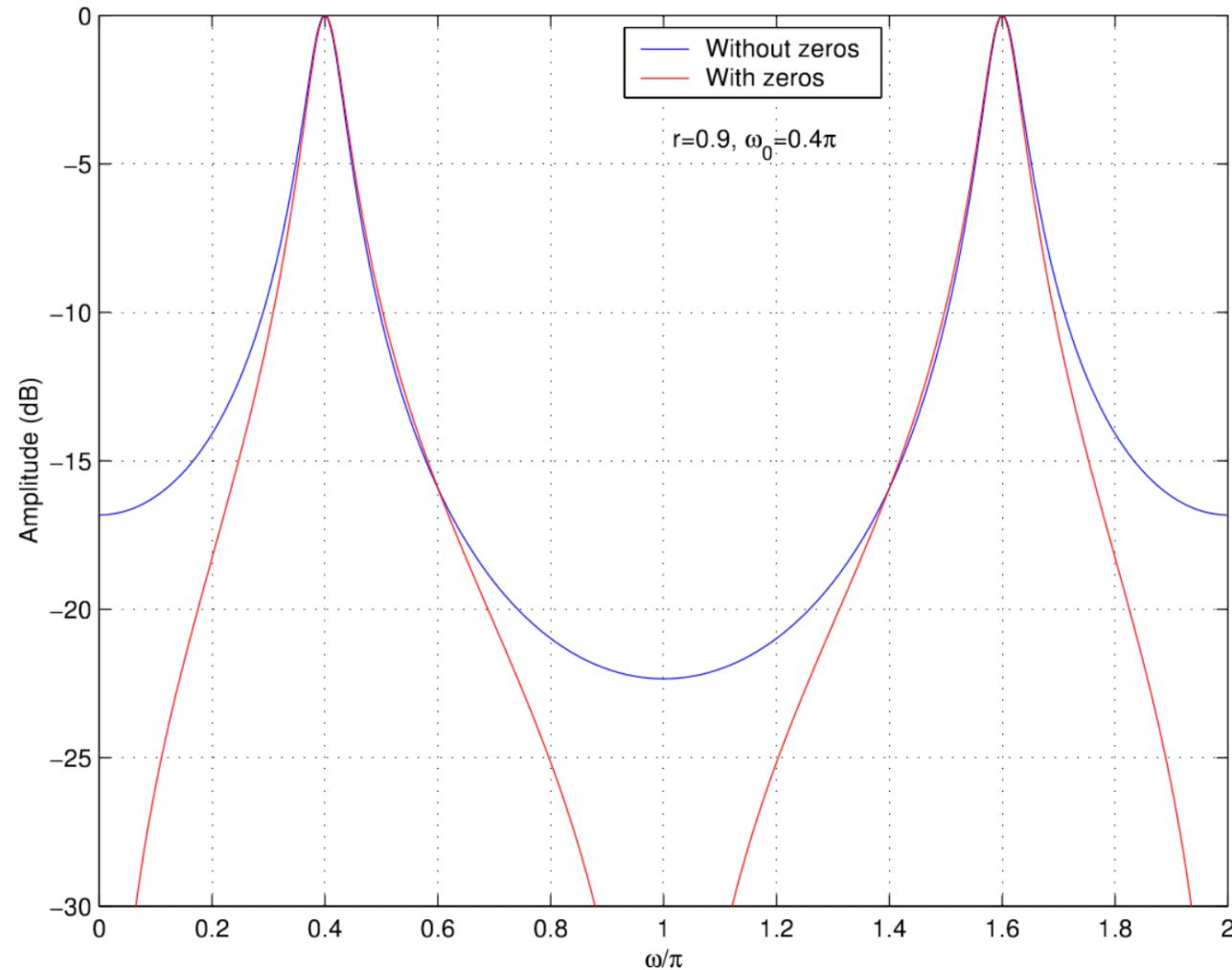


Can deepen nulls by introducing zeros at  $z = \pm 1$ :

$$H(z) = \frac{b_0(1 - z^{-2})}{1 - (2r \cos \omega_0)z^{-1} + r^2 z^{-2}} = \frac{b_0(1 - z^{-1})(1 + z^{-1})}{(1 - re^{j\omega_0}z^{-1})(1 - re^{-j\omega_0}z^{-1})}$$

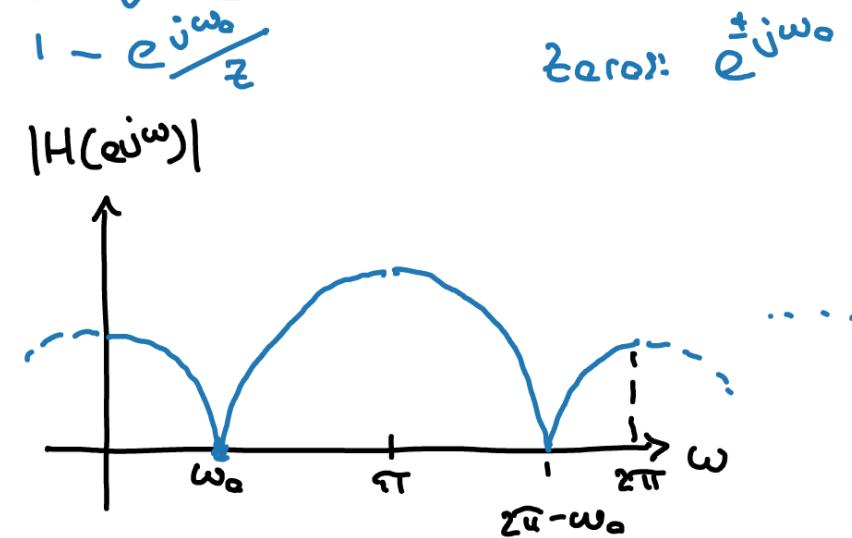
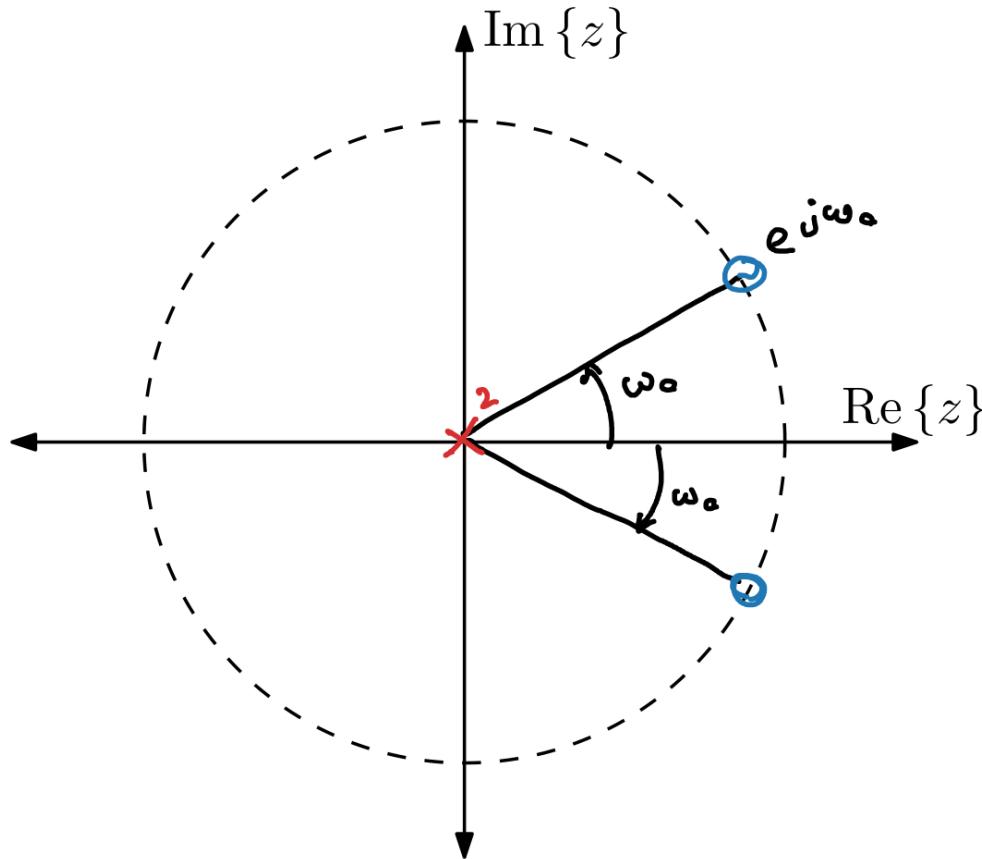


Digital resonator with and without zeros at  $\omega = 0$  and  $\pi$



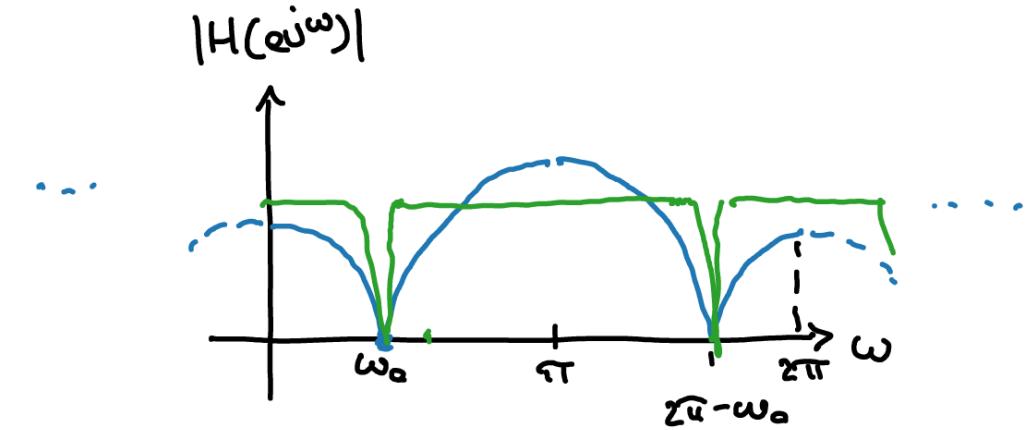
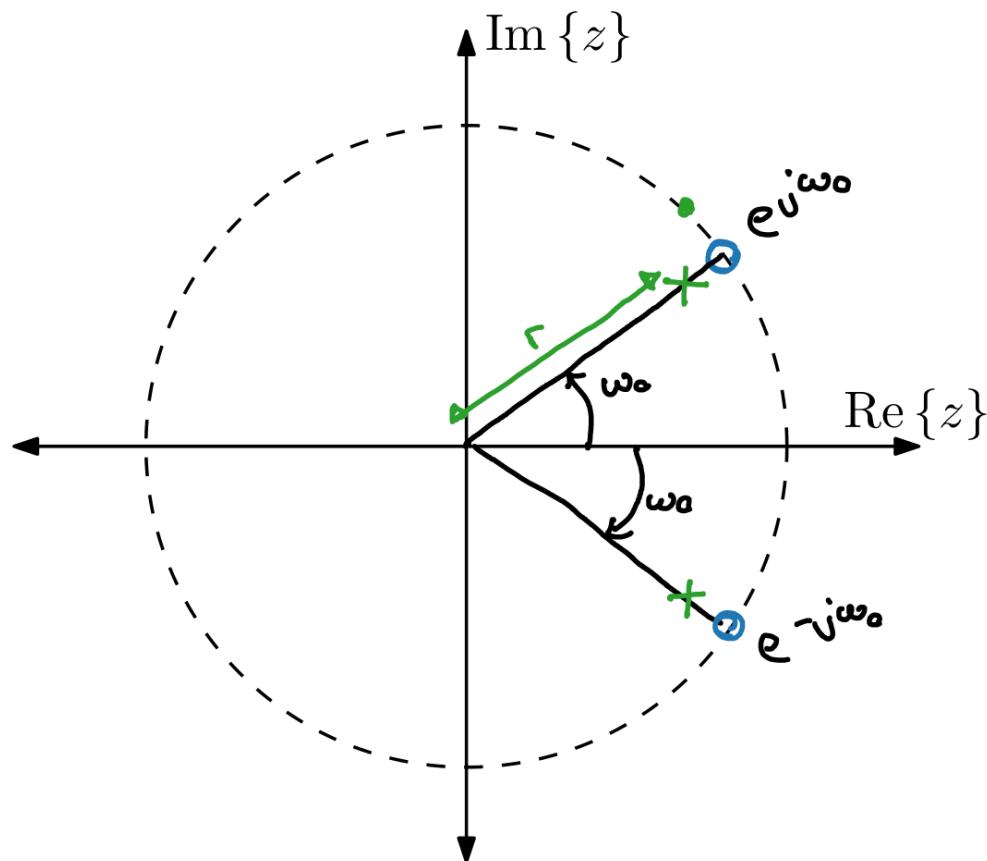
# Notch filter: An elementary BSF

$$H(z) = b_0(1 - (2 \cos \omega_0)z^{-1} + z^{-2}) = b_0 \left(1 - e^{j\omega_0} z^{-1}\right) \left(1 - e^{-j\omega_0} z^{-1}\right)$$

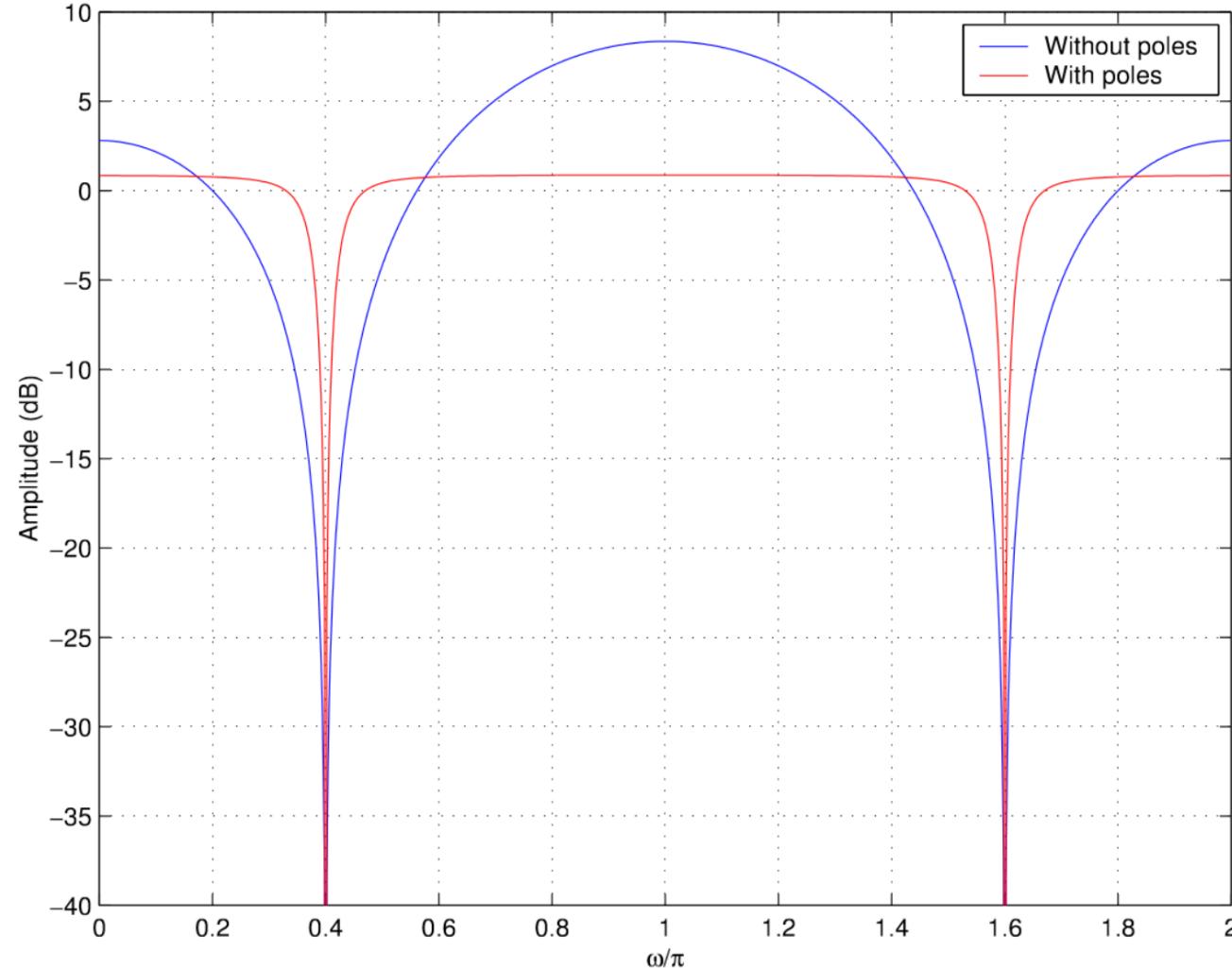


Bandwidth of notches can be reduced by placing a pole at the same frequency close to the unit circle:

$$H(z) = b_0 \frac{1 - (2 \cos \omega_0)z^{-1} + z^{-2}}{1 - (2r \cos \omega_0)z^{-1} + r^2 z^{-2}} = b_0 \frac{(1 - e^{j\omega_0} z^{-1})(1 - e^{-j\omega_0} z^{-1})}{(1 - re^{j\omega_0} z^{-1})(1 - re^{-j\omega_0} z^{-1})}$$

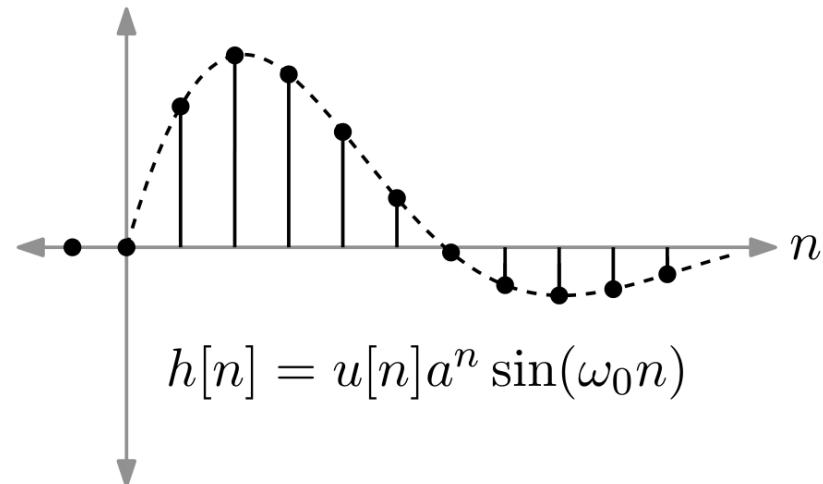


Digital notch filter with and without resonating poles ( $r = 0.9$ )



# Why not put poles as close as possible to unit circle?

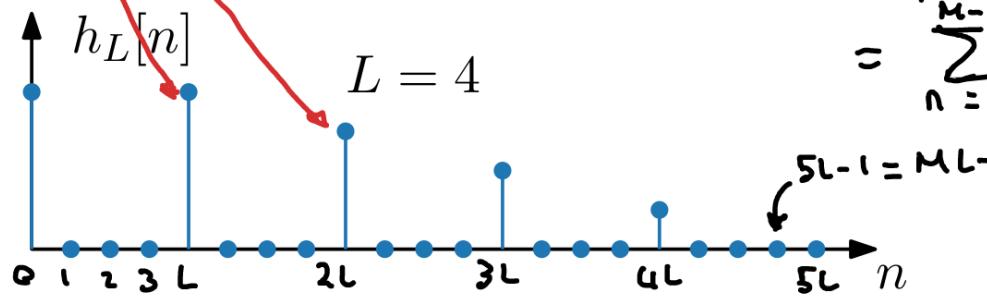
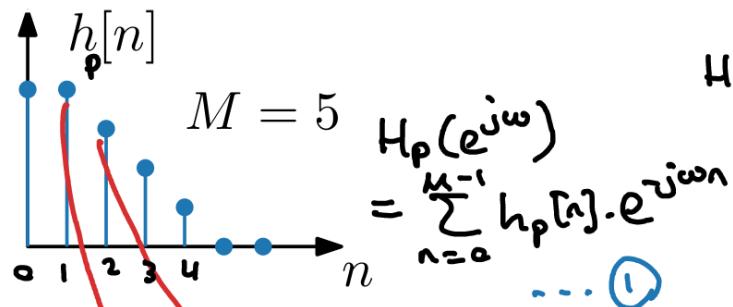
- The derivation that  $y[n] = H(e^{j\omega})e^{j\omega n} = |H(e^{j\omega})|e^{j\omega n + \angle H(e^{j\omega})}$  is for steady state
- This does not take transient effects into account
- What happens below when  $a$  gets close to 1? (similar for damped cosine)



$$\begin{aligned} H(z) &= \frac{(a \sin \omega_0) z^{-1}}{1 - (2a \cos \omega_0) z^{-1} + a^2 z^{-2}} \\ &= \frac{(a \sin \omega_0) z^{-1}}{(1 - ae^{j\omega_0} z^{-1})(1 - ae^{-j\omega_0} z^{-1})} \end{aligned}$$

$$|z| > |a|$$

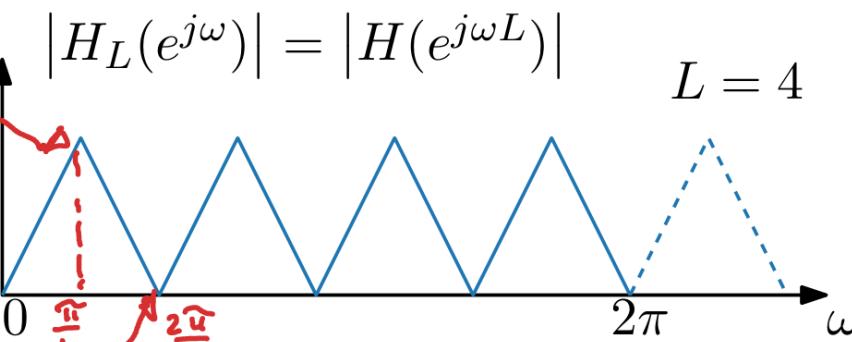
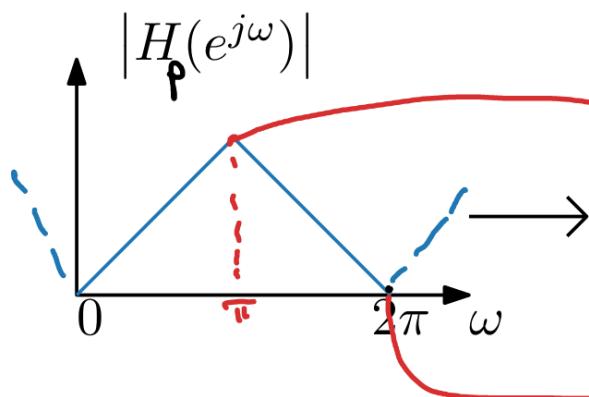
# Comb filter



$$\begin{aligned}
 H_L(z) &= \sum_{n=0}^{ML-1} h_L[n] \cdot z^{-n} \\
 &= h_L[0] \cdot z^0 + h_L[1] z^{-1} + h_L[2] z^{-2} + h_L[3] z^{-3} + h_L[4] z^{-4} \\
 &\quad + \dots + h_L[L] z^{-L} + \dots h_L[2L] z^{-2L} + \dots h_L[3L] z^{-3L} + \dots + h_L[4L] z^{-4L} \\
 &= h_p[0] \cdot z^0 + h_p[1] z^{-L} + h_p[2] z^{-2L} + h_p[3] z^{-3L} \\
 &= \sum_{n=0}^{M-1} h_p[n] \cdot z^{-nL}
 \end{aligned}$$

$H_L(e^{j\omega}) = \sum_{n=0}^{M-1} h_p[n] \cdot e^{-jn\omega L}$

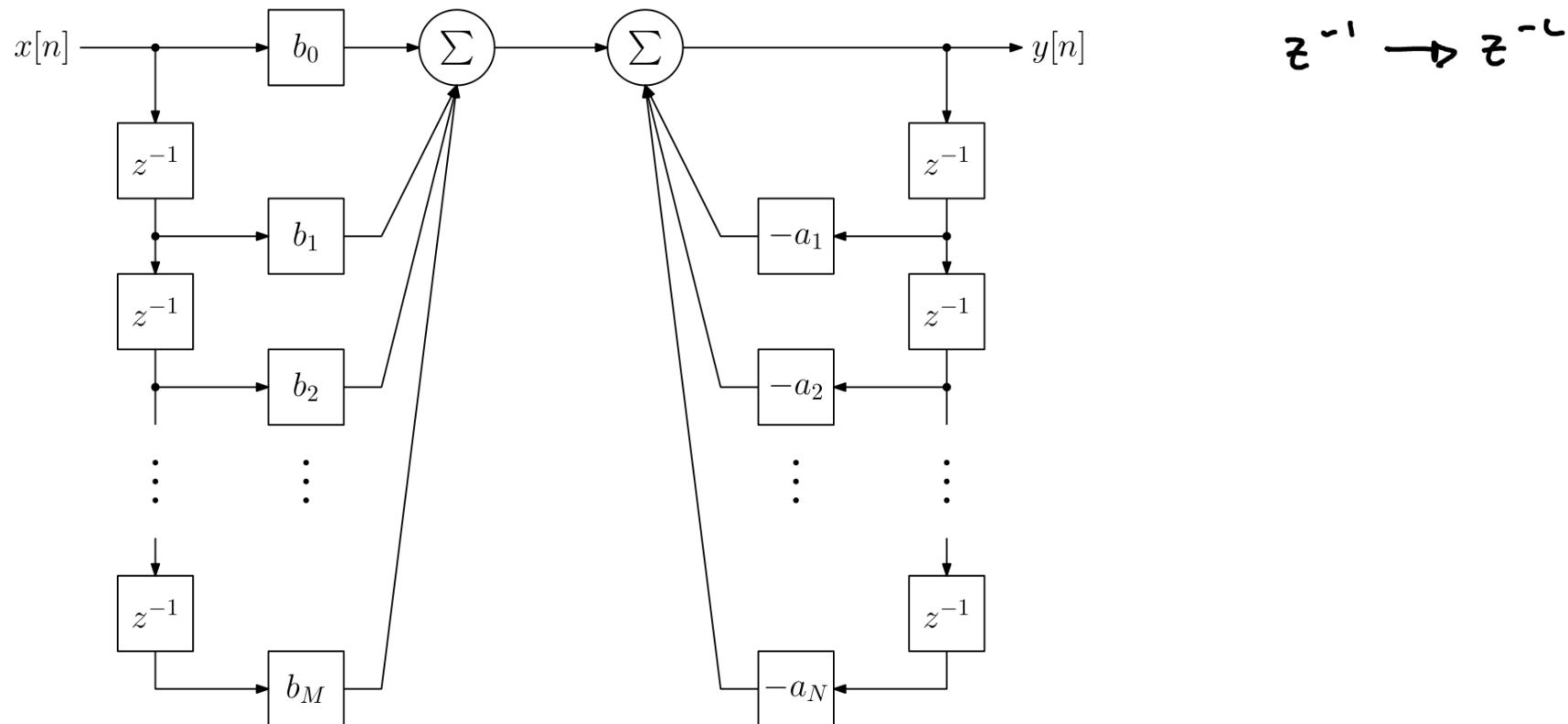
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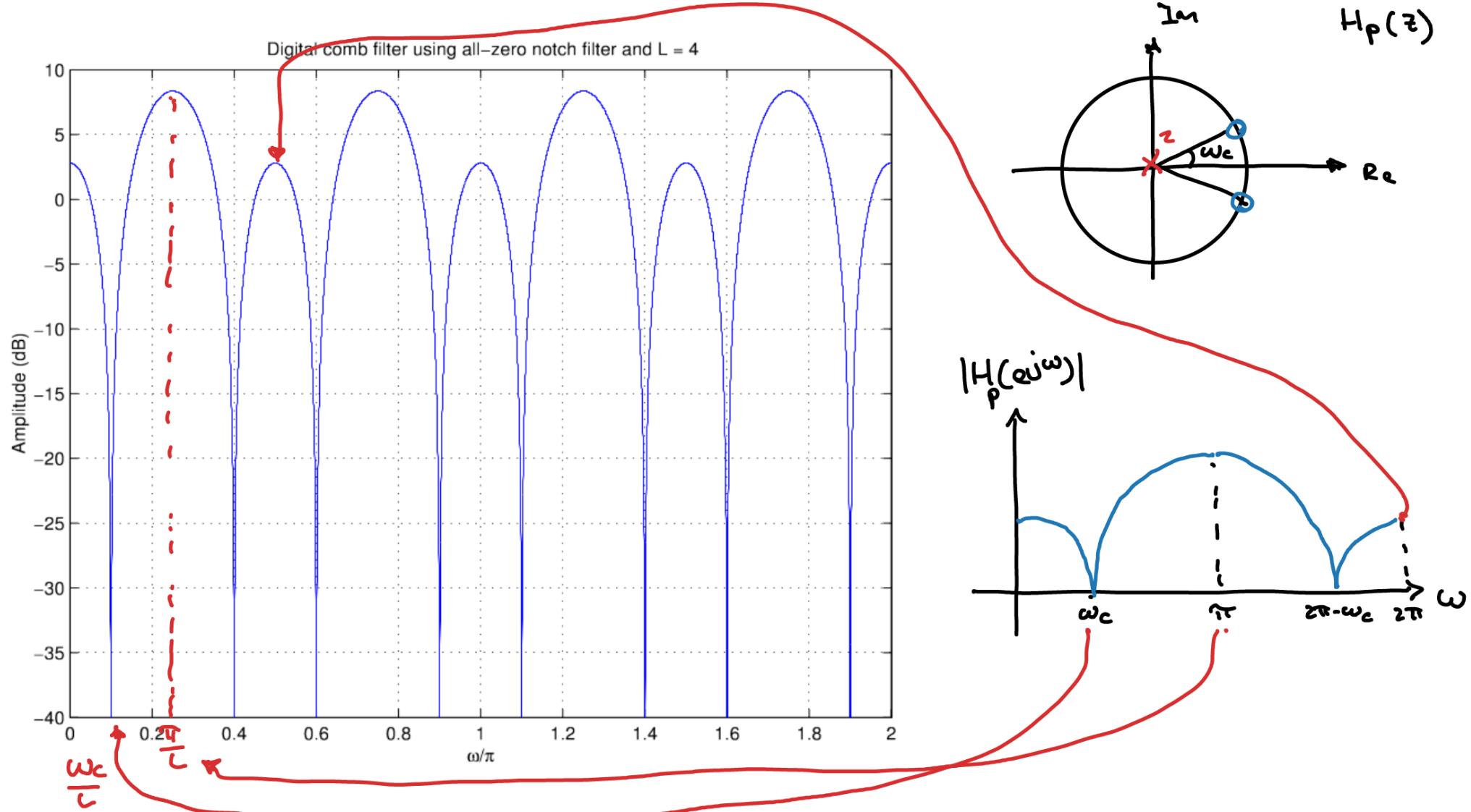


$x(t)$   
 $y(t) = x(\underline{\alpha}t)$

# Comb filter

$$\underline{b}_p = [1, 0, -1] \xrightarrow{L=4} \underline{b}_c = [1, 0, 0, 0, 0, 0, 0, -1]$$





# Why don't we just use the FFT to filter?

- Take the FFT of a signal
- Zero out the components we do not want
- Take the IFFT