


Overlap-and-add for fast linear filtering

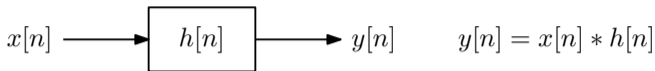
Fast convolution with streaming input

FIR filters



Herman Kamper

Linear filtering using the FFT

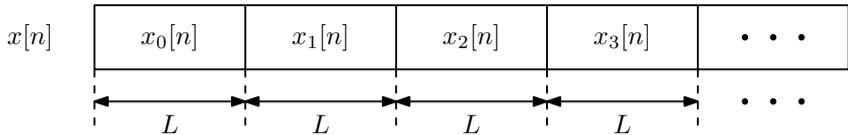


Calculate the discrete convolution using the FFT:

- Length of $x[n]$ is M
- Length of $h[n]$ is P (FIR)
- Zero pad $x[n]$ and $h[n]$ to length $N \geq M + P - 1$
- $y[n] = \text{IFFT} \{X_{\text{zp}}[k] \cdot H_{\text{zp}}[k]\}$

Zero padding

But $x[n]$ is often streamed in, i.e. not bounded in length.



Overlap-and-add

$$x[n] = \sum_{i=0}^{\infty} x_i[n] \quad \text{where } x_i[n] = \begin{cases} x[n] & \text{if } n \text{ is window } i \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} y[n] &= h[n] * x[n] = h[n] * \left(\sum_{i=0}^{\infty} x_i[n] \right) \\ &= \sum_{i=0}^{\infty} h[n] * x_i[n] \\ &= \sum_{i=0}^{\infty} y_i[n] \quad \text{where } y_i[n] = h[n] * x_i[n] \end{aligned}$$

$$y_0[n] = h[n] * x_0[n]$$



$n = 0:$



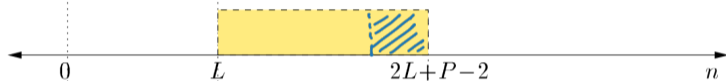
$n = ? :$



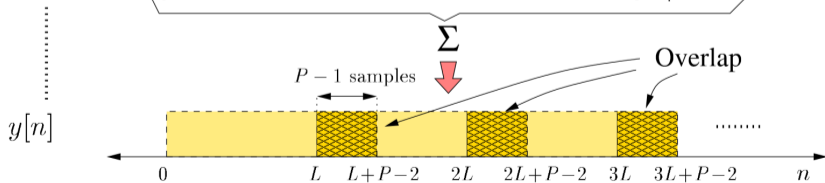
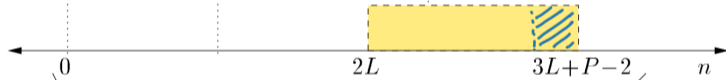
$$x_0[n] * h[n] = y_0[n]$$

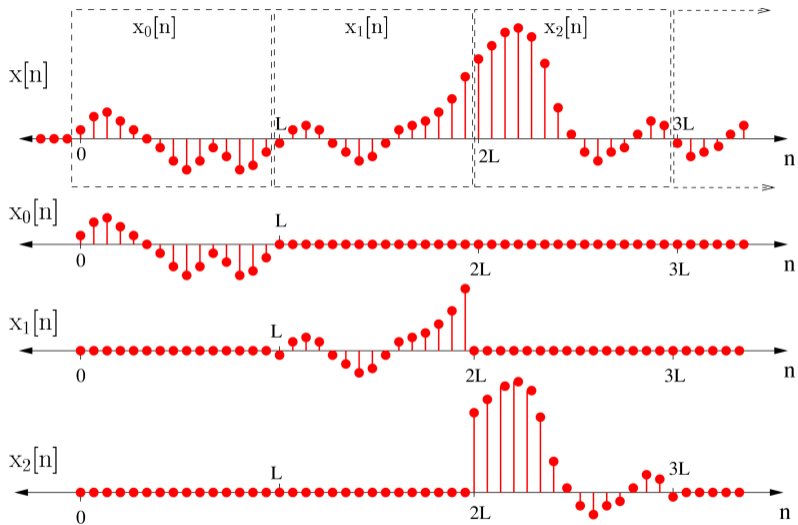


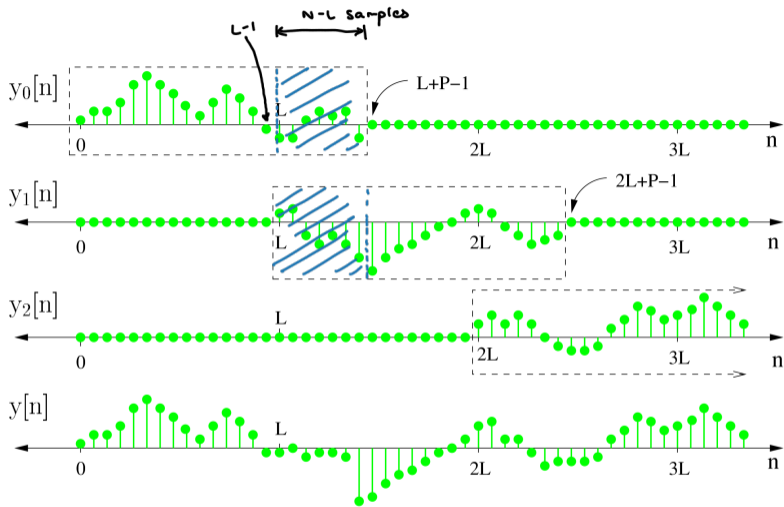
$$x_1[n] * h[n] = y_1[n]$$





$$x_2[n] * h[n] = y_2[n]$$







Overlap-and-add procedure

- Choose a suitable block length L
- Zero pad $h[n]$ to length $N \geq L + P - 1$
- Calculate $H[k] = \text{FFT}\{h[n]\}$

- For each L -sample block of the input sequence:
 - Zero pad to length N
 - Calculate the FFT
 - Multiply with $H[k]$
 - Calculate the IFFT

 - Add to $y[n]$, overlapping the last $N - L$ samples
- Final result: $y[n]$

$$y_i[n] = x_i[n] * h[n]$$

Overlap-and-add is more efficient than direct when $P \gg 64$