Test slide

- Is there a chat box?
- Can you see my pointer?
- Can you hear this: Play

Learning acoustic units and words from unlabelled speech (with a bit of vision)

CLSP Seminar, Johns Hopkins University, Oct. 2020

Herman Kamper

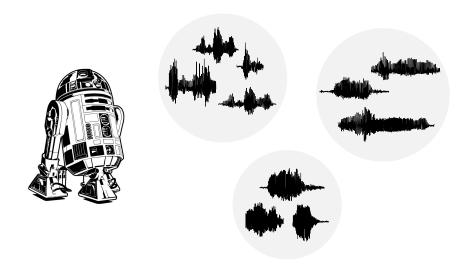
E&E Engineering, Stellenbosch University, South Africa http://www.kamperh.com/

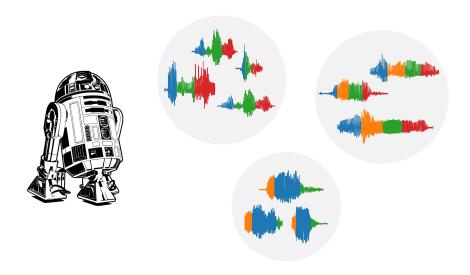
















Bootstrap low-resource speech technology



Bootstrap low-resource speech technology



Applications such as non-parallel voice conversion



Bootstrap low-resource speech technology



Applications such as non-parallel voice conversion



 $Cognitive \ models \ of \ language \ acquisition$



Bootstrap low-resource speech technology



Applications such as non-parallel voice conversion



Cognitive models of language acquisition



New insights and modelling approaches

Experience Grounds Language

Yonatan Bisk* Ari Holtzman* Jesse Thomason*

Jacob Andreas Yoshua Bengio Joyce Chai Mirella Lapata

Angeliki Lazaridou Jonathan May Aleksandr Nisnevich Nicolas Pinto Joseph Turian

Experience Grounds Language

Yonatan Bisk* Ari Holtzman* Jesse Thomason*

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You can't learn language ...

... from the radio (internet). $WS2 \subset WS3$

A learner cannot be said to be in WS3 if it can perform its task without sensory perception such as visual, auditory, or tactile information.

... from a television. $WS3 \subset WS4$

A learner cannot be said to be in WS4 if the space of actions and consequences of its environment can be enumerated.

... by yourself. $WS4 \subset WS5$

A learner cannot be said to be in WS5 if its cooperators can be replaced with cleverly pre-programmed agents to achieve the same goals.

Experience Grounds Language

Yonatan Bisk* Ari Holtzman* Jesse Thomason*

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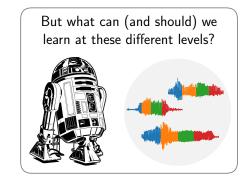
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1. Vector-quantised neural networks for unsupervised acoustic unit discovery

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Benjamin van Niekerk



Leanne Nortje

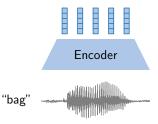
1. Vector-quantised neural networks for unsupervised acoustic unit discovery

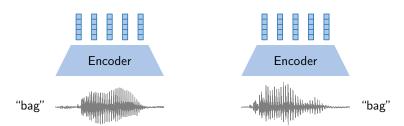


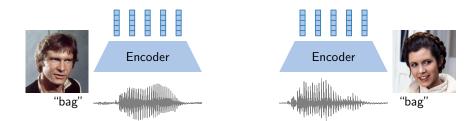
Benjamin van Niekerk

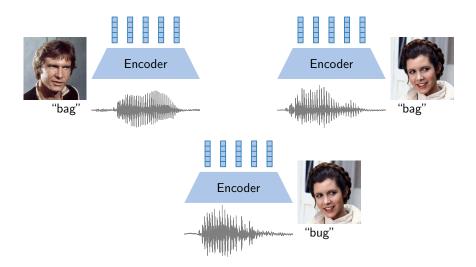


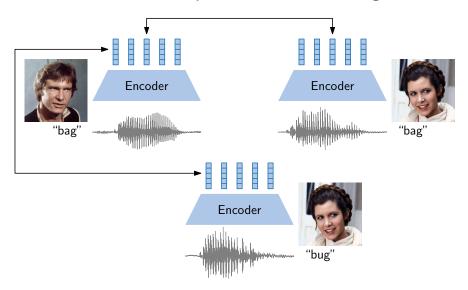
Leanne Nortje

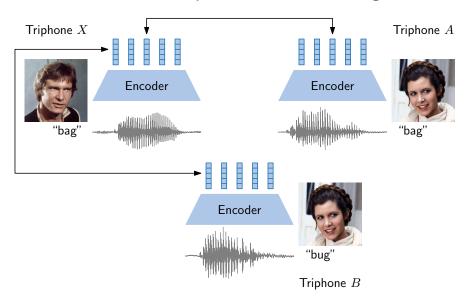


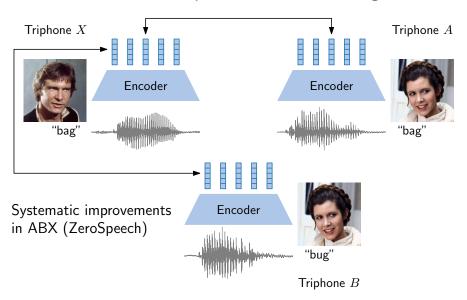




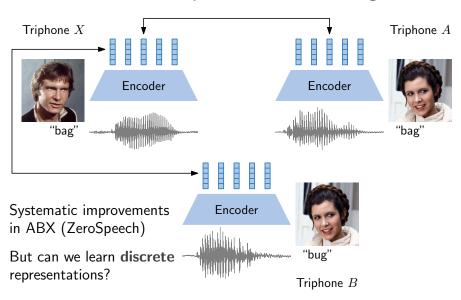




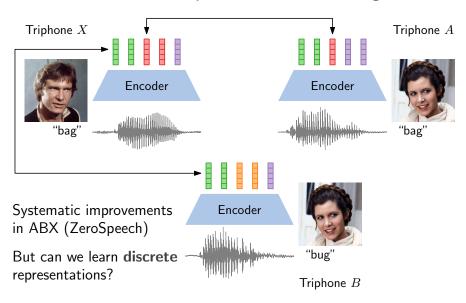


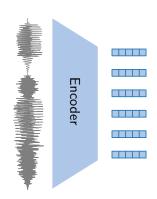


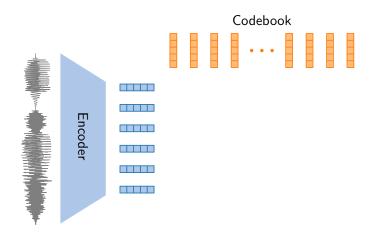
Phonetic representation learning

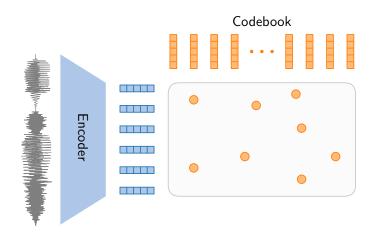


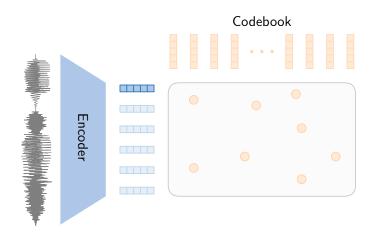
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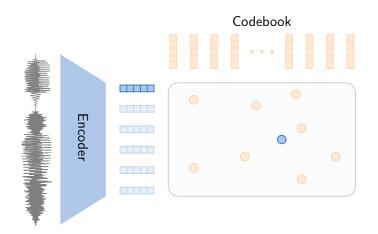


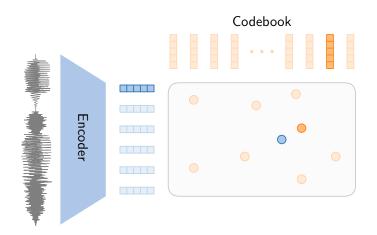


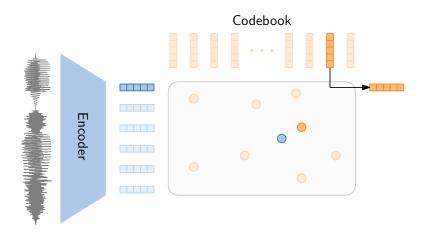


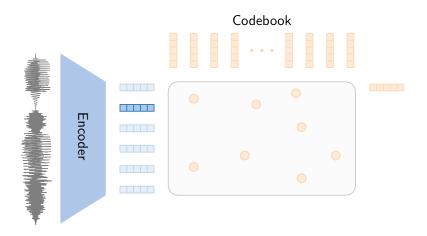


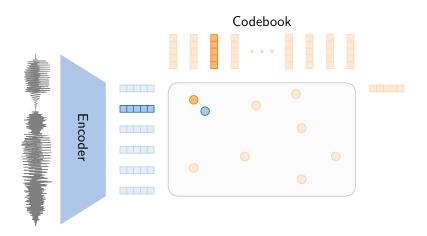


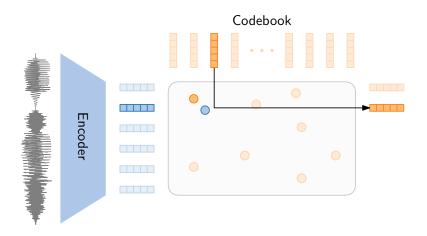


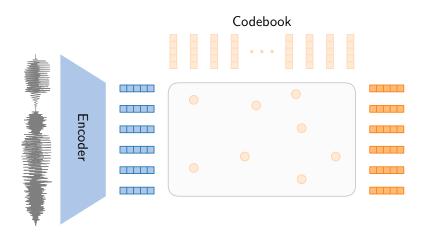


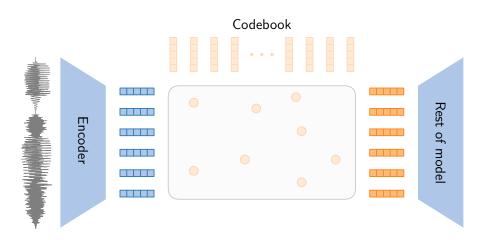










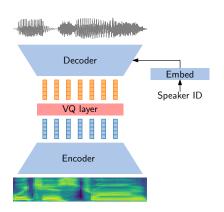


Our contribution

We propose and compare two models for unsupervised acoustic unit discovery:

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We propose and compare two models for unsupervised acoustic unit discovery:



VQ-VAE: A vector-quantised variational autoencoder

Inspired by:

Chorowski, et al., "Unsupervised speech representation learning using wavenet autoencoders," *TASLP*, 2019.

Van Niekerk et al., "Vector-quantized neural networks for acoustic unit discovery in the ZeroSpeech 2020 challenge," Interspeech, 2020.

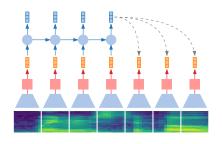
Our contribution

We propose and compare two models for unsupervised acoustic unit discovery:

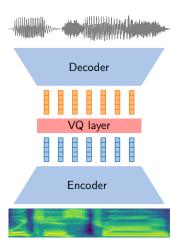
VQ-CPC: Combining vector quantisation with contrastive predictive coding

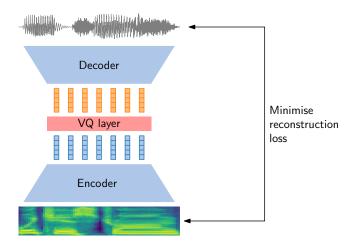
Inspired by:

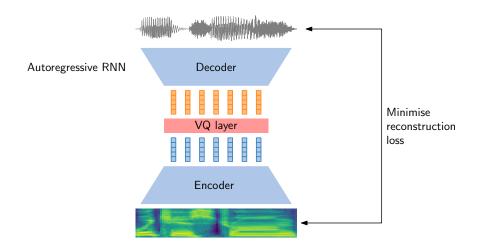
Van den Oord, et al., "Representation learning with contrastive predictive coding," arXiv, 2018.

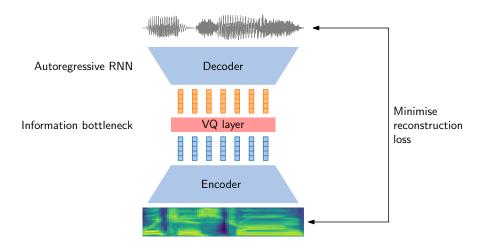


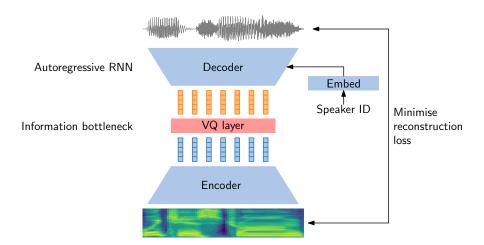
Van Niekerk et al., "Vector-quantized neural networks for acoustic unit discovery in the ZeroSpeech 2020 challenge," Interspeech, 2020.

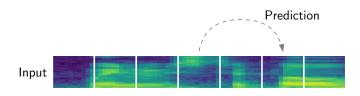


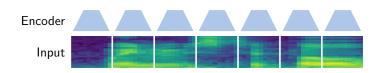


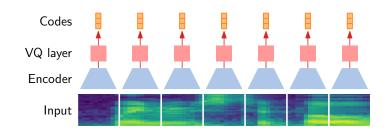


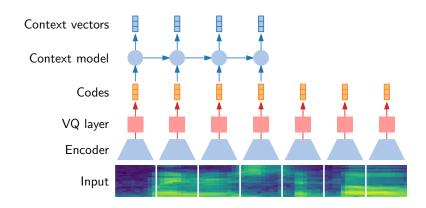


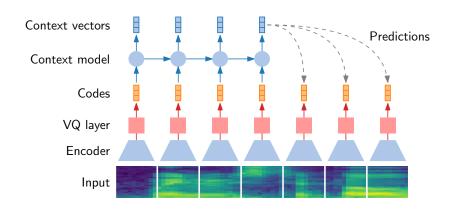


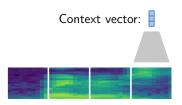


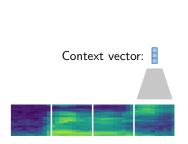




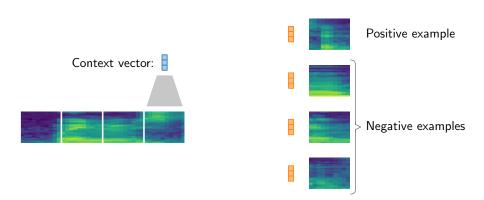


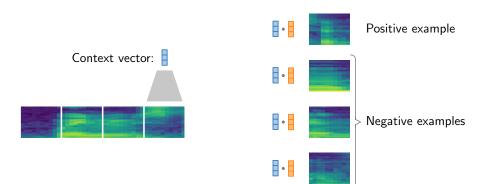


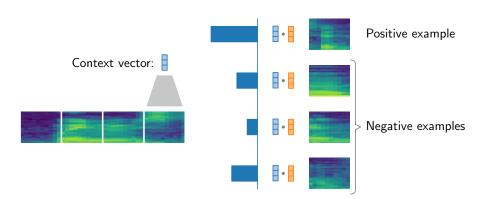




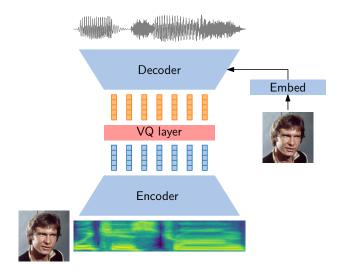




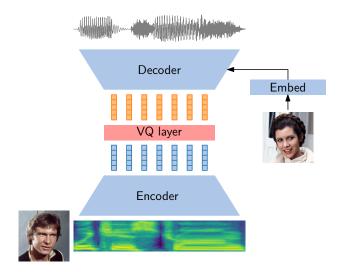




Evaluation: Voice conversion



Evaluation: Voice conversion



Example conversions

Example 1:

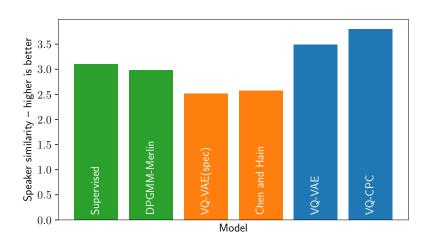
- Source: Play
- Converted: Play
- Target: Play

Example 2:

- Source: Play
- Converted: Play
- Target: Play

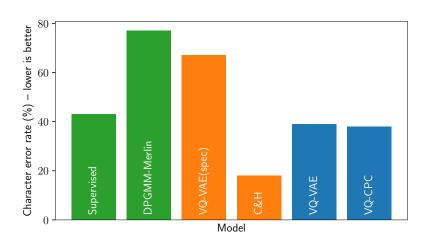
Evaluation: Speaker similarity

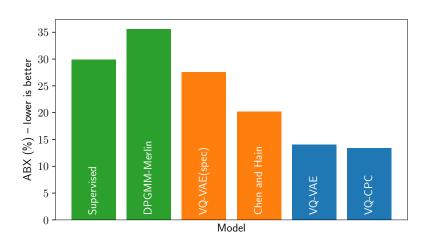
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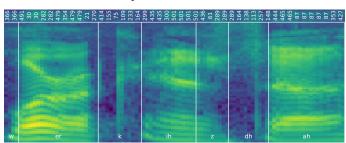
Chen and Hain, "Unsupervised acoustic unit representation learning for voice conversion using WaveNet auto-encoders," Interspeech, 2020.

Evaluation: Intelligibility

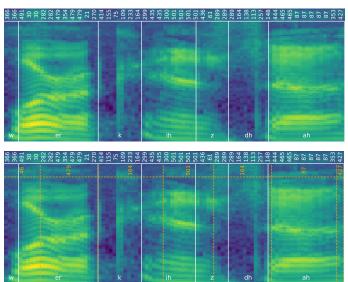




VQ-CPC codes

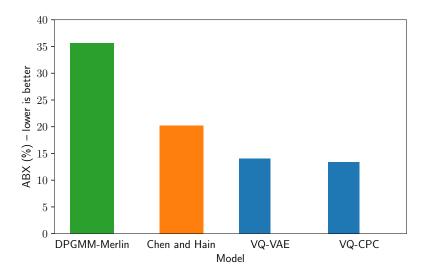


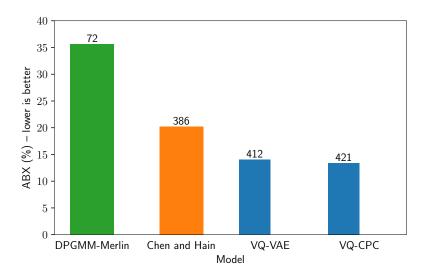
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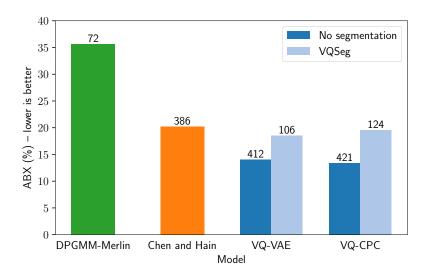


Inspired by:

Chorowski et al., "Unsupervised neural segmentation and clustering for unit discovery in sequential data," PGR Workshop, 2019.







Levels of language learning (for word and phone acquisition)

1. What can we learn from unlabelled speech audio, i.e. radio?

— Part 1

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2. Multimodal few-shot learning from images and speech

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Ryan Eloff



Herman Engelbrecht



Leanne Nortje

2. Multimodal few-shot learning from images and speech



Ryan Eloff



Herman Engelbrecht



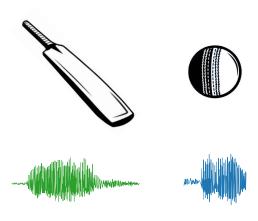
Leanne Nortje

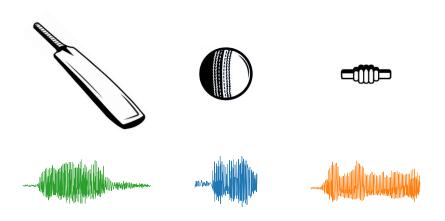
















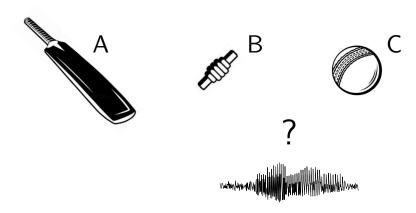


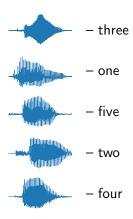




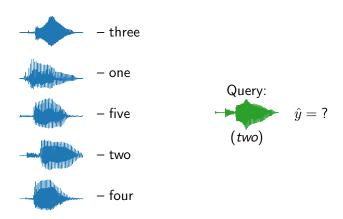


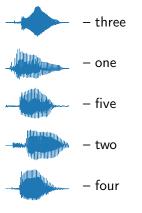






Fei-Fei et al., "One-shot learning of object categories," *TPAMI*, 2006. Lake et al., "One-shot learning of generative speech concepts," *CogSci*, 2014.

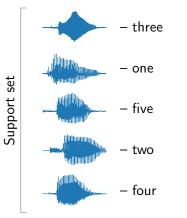




One-shot speech learning

Query:
$$\hat{y} = ?$$
 (two)

One-shot speech classification

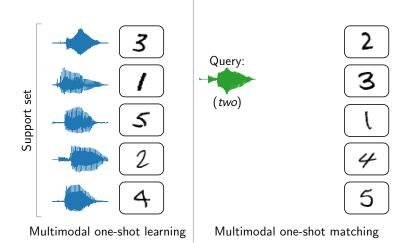


Query: $\hat{y} = ?$ (two)

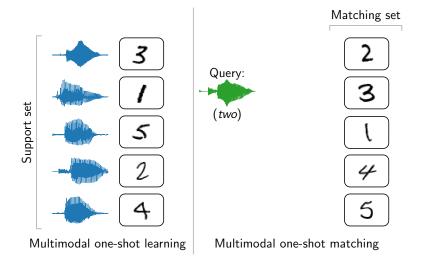
One-shot speech learning

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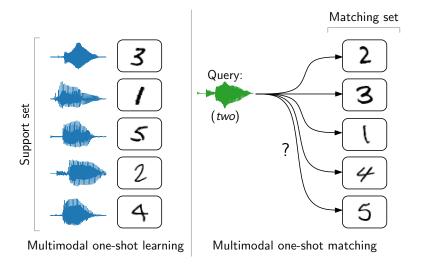
Multimodal one-shot learning and matching

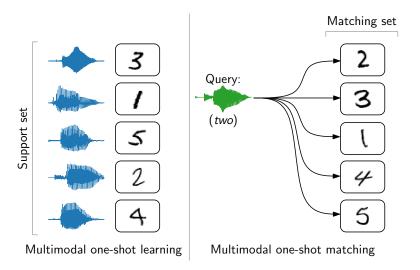


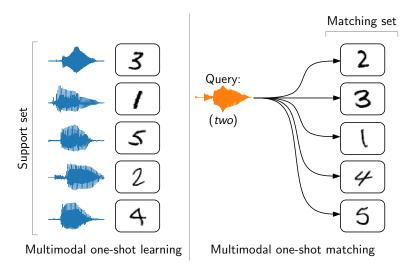
Multimodal one-shot learning and matching

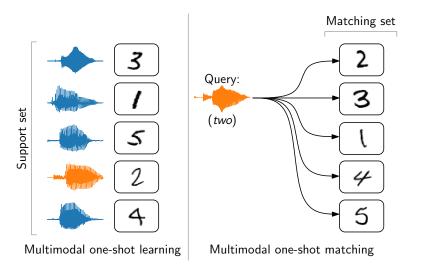


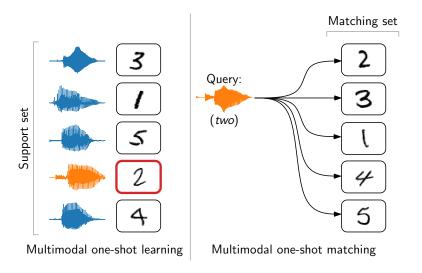
Multimodal one-shot learning and matching

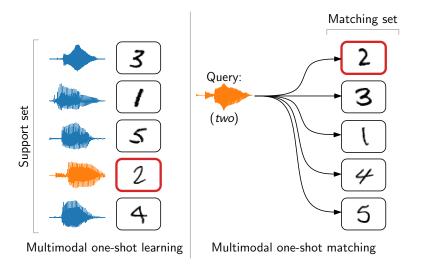


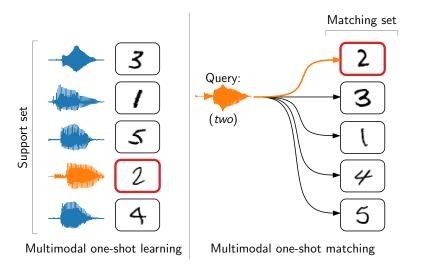




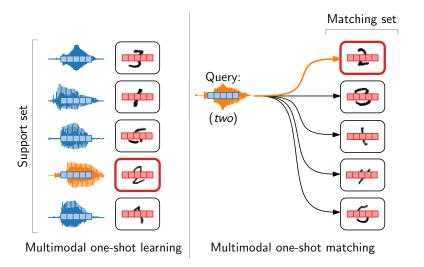








Two-step (indirect) multimodal one-shot approach



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- Requires within-modality speech-to-speech and image-to-image distance metrics
- Baseline: DTW over speech, cosine over image pixels
- Or representations/distance metrics can be learned

Two-step (indirect) multimodal one-shot approach

- Requires within-modality speech-to-speech and image-to-image distance metrics
- Baseline: DTW over speech, cosine over image pixels
- Or representations/distance metrics can be learned
- Compare two learning methodologies on TIDigits (speech) paired with MNIST (images)

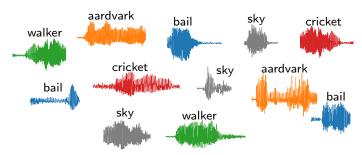
1. Transfer learning from labelled background data

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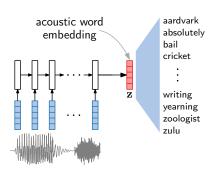
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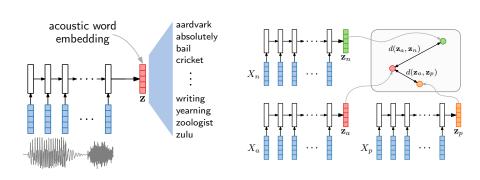
Isolated labelled words (no digits):



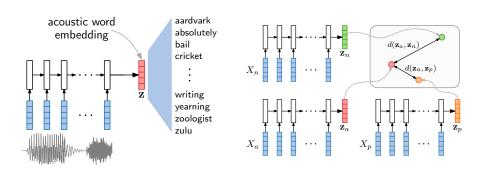
1. Supervised models for transfer learning



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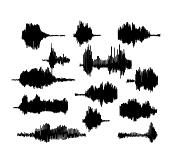


1. Supervised models for transfer learning



2. Unsupervised learning from unlabelled in-domain data

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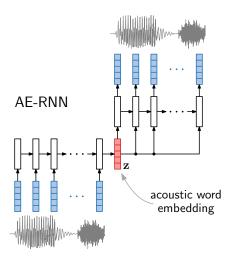
Unlabelled speech



2 9 1 5 4 4 7 6 9 1 0 2 4 5 3 4

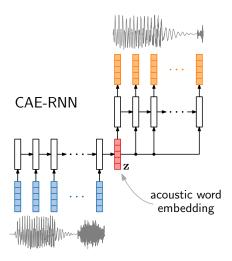
Unlabelled images

2. Unsupervised models



Chung et al., "Unsupervised learning of audio segment representations using sequence-to-sequence recurrent neural networks," Interspeech, 2016.

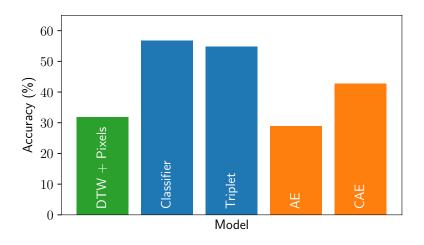
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Kamper, "Truly unsupervised acoustic word embeddings using weak top-down constraints in encoder-decoder models," ICASSP. 2019.

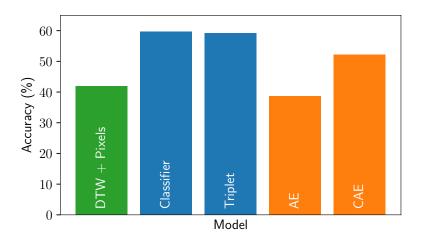
Evaluation: Multimodal one-shot matching

Evaluation: Multimodal one-shot matching



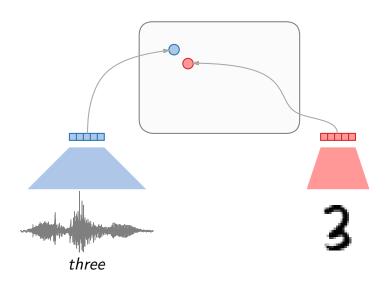
Nortje and Kamper, "Unsupervised vs. transfer learning for multimodal one-shot matching of speech and images," Interspeech, 2020.

Evaluation: Multimodal five-shot matching

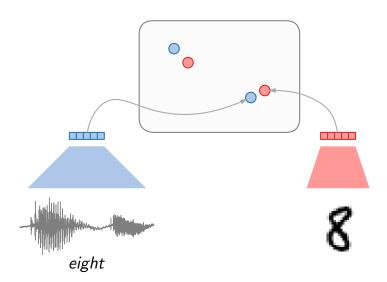


Nortje and Kamper, "Unsupervised vs. transfer learning for multimodal one-shot matching of speech and images," Interspeech, 2020.

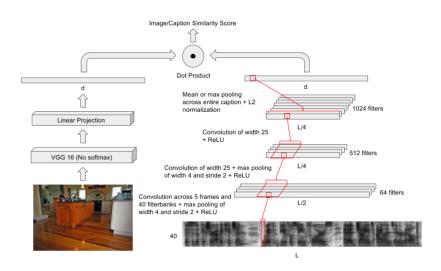
3. A direct approach?

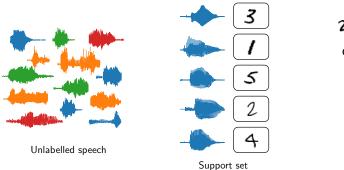


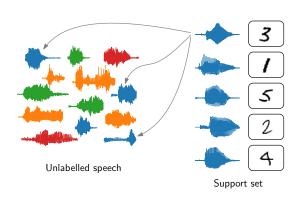
3. A direct approach?



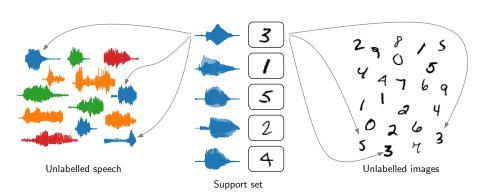
3. A direct approach?

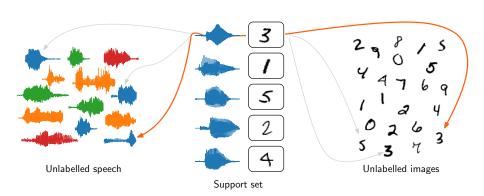


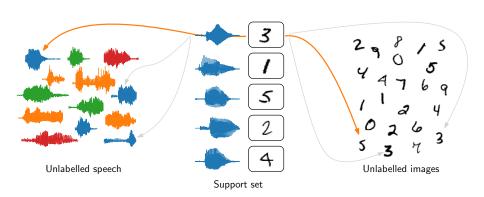


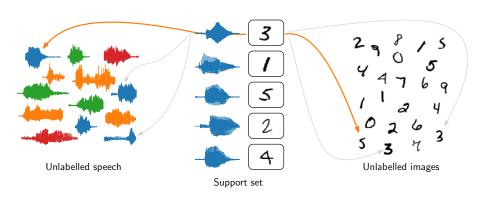






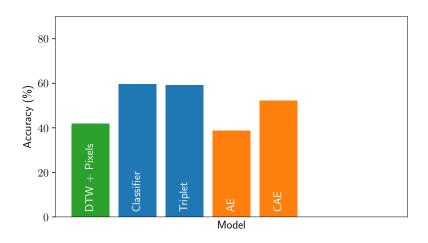




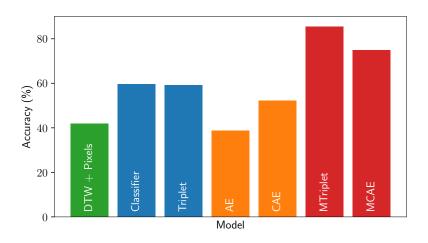


Involves combining (1) transfer learning and (2) unsupervised learning

Evaluation: Multimodal five-shot matching



Evaluation: Multimodal five-shot matching



Summary and conclusion

Summary and looking forward

1. What can we learn from unlabelled speech audio, i.e. radio? — Part $\bf 1$

2. What can we learn from co-occurring (grounding) signals like vision, i.e. television? — Part 2

3. What can we learn from interaction/feedback from our environment and other "agents"?

Summary and looking forward

- 0. What structures/knowledge should we start with/build in?
- What can we learn from unlabelled speech audio, i.e. radio?
 Part 1
- What can we learn from co-occurring (grounding) signals like vision, i.e. television?

 Part 2
- 3. What can we learn from interaction/feedback from our environment and other "agents"?

https://github.com/bshall/ZeroSpeech/
https://github.com/bshall/VectorQuantizedCPC/
https://github.com/LeanneNortje/multimodal_speech-image_matching/

